

Friedrich-Alexander-Universität, Erlangen-Nürnberg

# Multiple DCLC Routing Algorithms for Ultra-Reliable and Time-Sensitive Applications

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Informatik 7 (Rechnernetze und Kommunikationssysteme)

# Outline

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- 01 Problem Statement
- 02 Delay Bounded Dijkstra's Algorithm
- 03 Multiple Disjoint Path Algorithm (MDPAlg)
  - 3.1 Construction of Cost Matrix
  - 3.2 Construction of Disjoint Paths
- 04 Results
- 05 Delay Constraints for Real-Time Communications
- 06 Conclusions

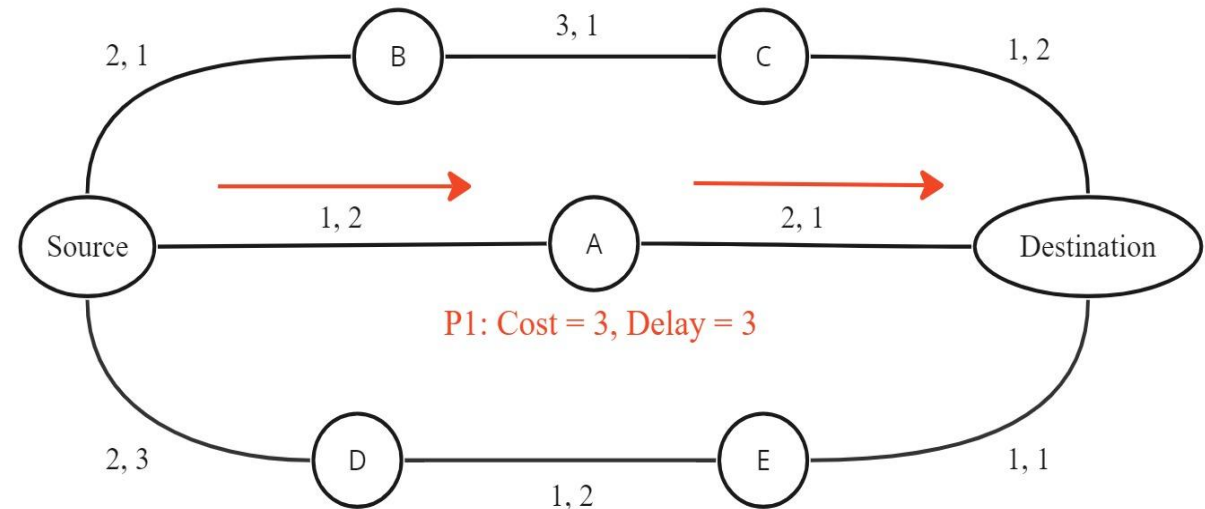
# Problem Statement

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- Time sensitive applications need highly **reliable** networks.
- In case of **faulty connection**, a new path needs to be configured to take over.
- All paths should have as **low cost** (weight) as possible.
- All paths should satisfy the **delay constraint**.
- **Objective:** Establish two or more disjoint shortest path from source to destination, considering both cost and delay requirements and simultaneously transmit data on all the paths to achieve ultra high reliability.

# Example of Disjoint Paths

- Link attributes: **Delay and Cost (weight)**.
- **Example:**
  - Generate two disjoint paths with least cost and max end-to-end delay of 5 units.

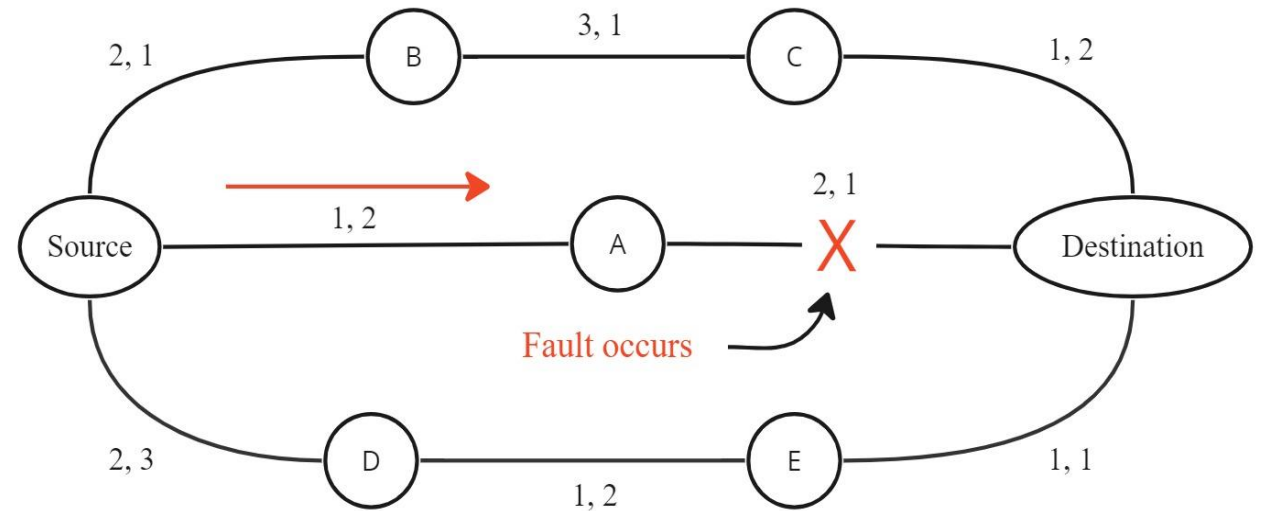


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**Path P1: Source - A - Destination (cost = 3, delay = 3 units).**

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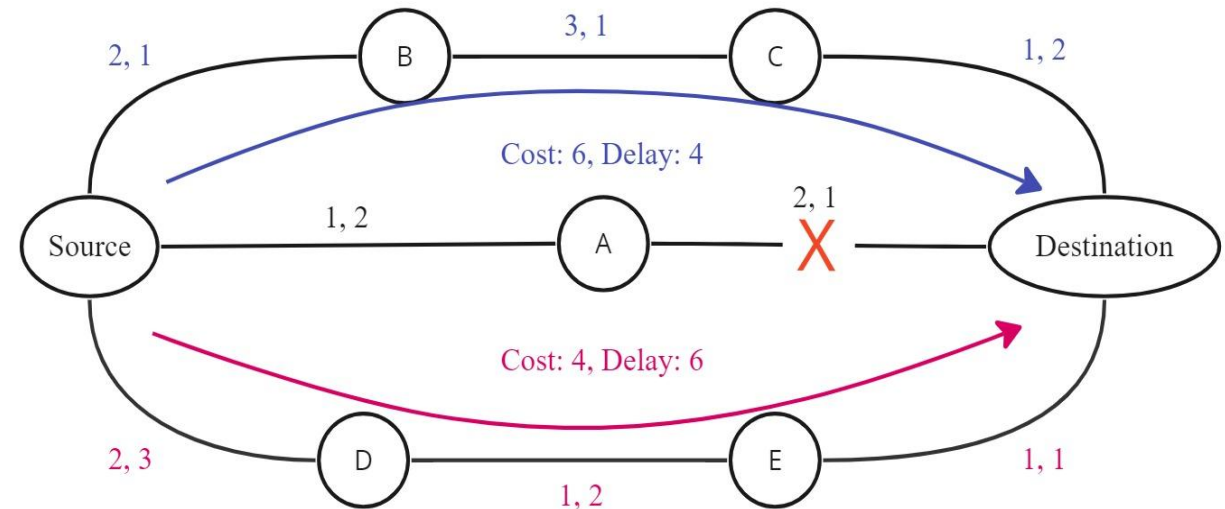


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**Path P1: Source - A - Destination (cost = 3, delay = 3 units).**

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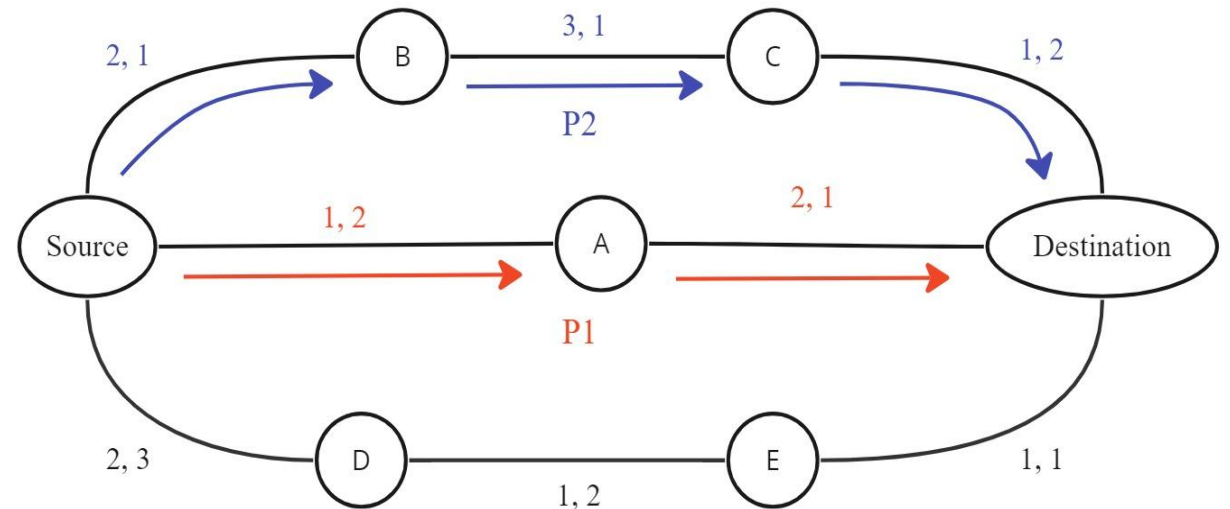
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**Path P2: Source - B - C - Destination (cost = 6, delay = 4 units).**

**Path P3: Source - D - E - Destination (cost = 5, delay = 6 units).**

# Example of Disjoint Paths

- Link attributes: **Delay and Cost (weight)**.
- **Example:**
  - Generate two disjoint paths with least cost and max end-to-end delay of 5 units.



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**Path P1: Source - A - Destination (cost = 3, delay = 3 units).**

**Path P2: Source - B - C - Destination (cost = 6, delay = 4 units).**

~~**Path P3: Source - D - E - Destination (cost = 5, delay = 6 units).**~~

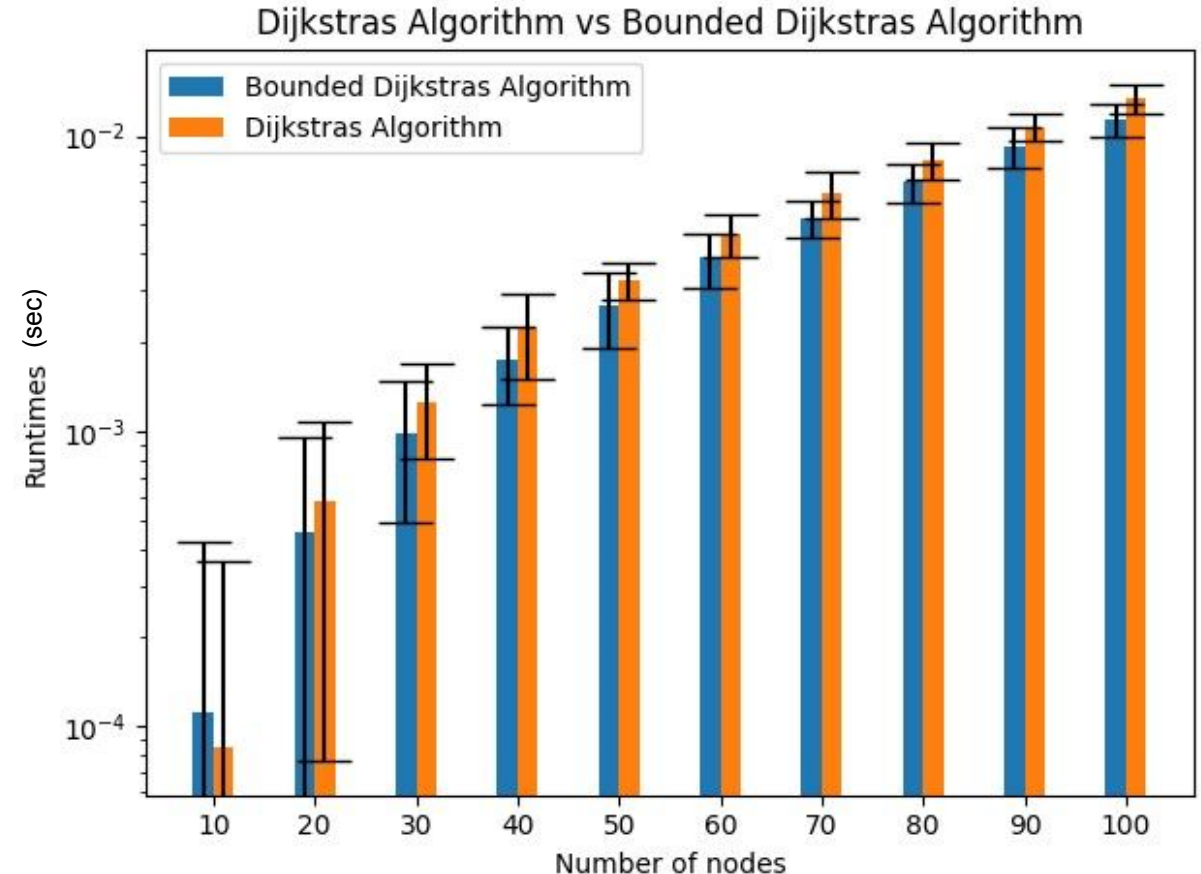
# Bounded Dijkstra's Algorithm<sup>1</sup>

1. Bentsen, A.V., Guck, J.W., Machuca, C.M., and Kellerer, W. (2019). Bounded Dijkstra (BD): Search Space Reduction for Expediting Shortest Path Subroutines. ArXiv, abs/1903.00436.



# Bounded Dijkstra's Algorithm

- Dijkstra's algorithm discovers paths in increasing order of cost.
- Delay values from source to other nodes are tracked in the same way as the weight is calculated in simple Dijkstra's.
- Additionally, a **delay threshold** is introduced.
- If this threshold exceeds, the corresponding cost is **not** updated.
- Thereby **reducing the search space and runtime.**



# Bounded Dijkstra's Algorithm

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**Drawbacks** of Bounded Dijkstra's:

- Running Dijkstra's algorithm multiple times makes them **computationally expensive**.
- Possibility of **not finding enough disjoint paths**.
- **Runtime increases** when more than two shortest paths are required.

# Multiple Disjoint Path Algorithm (MDPAI<sub>g</sub>)<sup>1</sup>

1. D. Lopez-Pajares, E. Rojas, J. A. Carral, I. Martinez-Yelmo and J. Alvarez-Horcajo, "The Disjoint Multipath Challenge: Multiple Disjoint Paths Guaranteeing Scalability," in IEEE Access, vol. 9, pp. 74422-74436, 2021.

# Multiple Disjoint Path Algorithm (MDPAlg)

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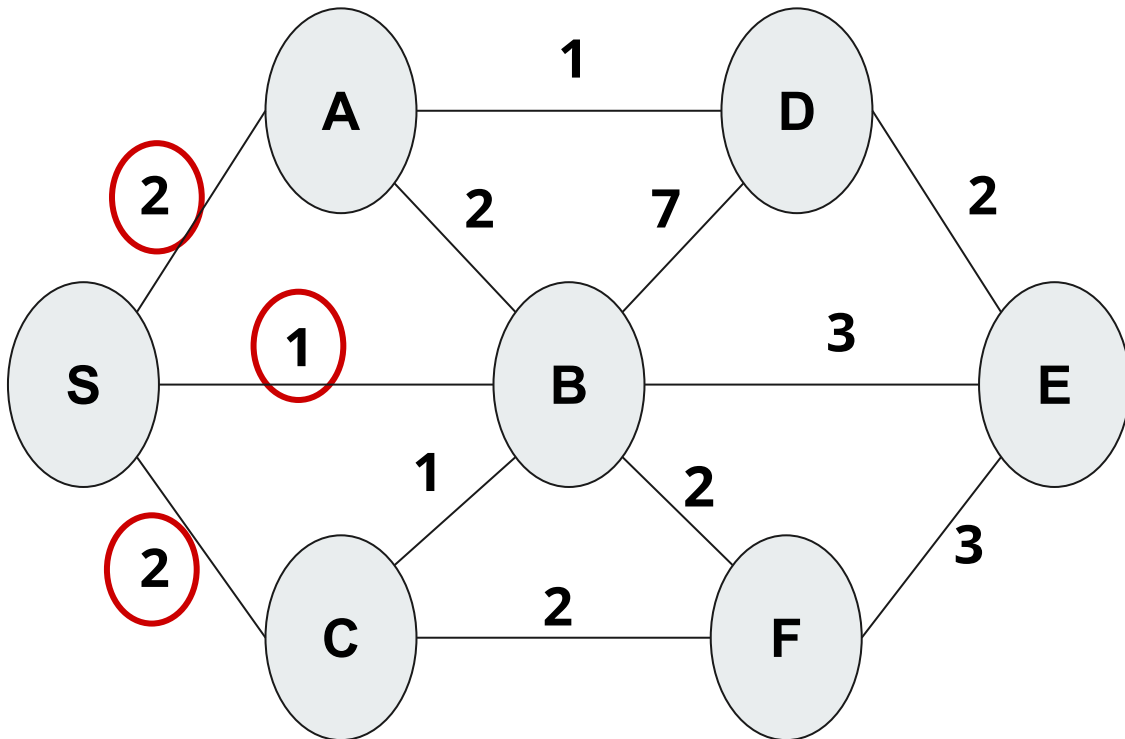
Two step algorithm:

- Construction of a **cost matrix**:
  - Requires a single full graph search.
  - Stores '**extra**' information compared to Dijkstra's.
- Construction of disjoint paths:

**Improvements**, over Bounded Dijkstra's, with MDPAlg:

- Does not make use of Dijkstra's algorithm.
- Guaranteed to extract **maximum** number of disjoint paths possible.

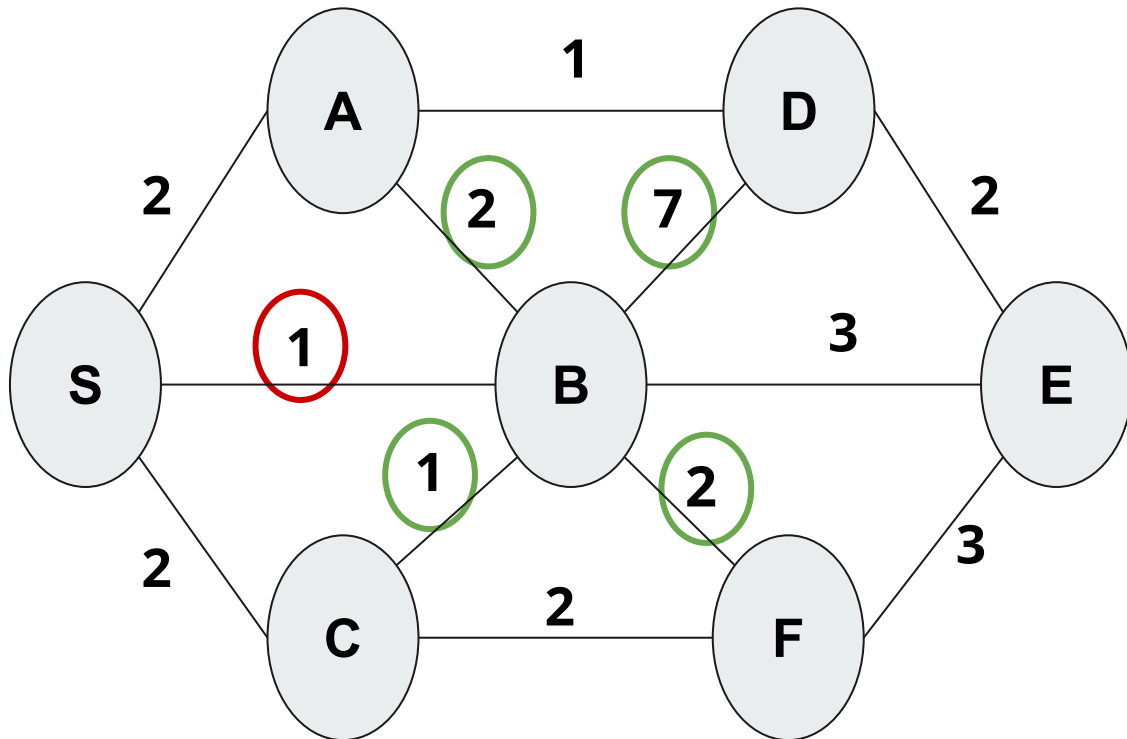
# Step 1: Construction of Cost Matrix



	S	A	B	C	D	E	F
S		2	1	2			
A							
B							
C							
D							
E							
F							

COST MATRIX

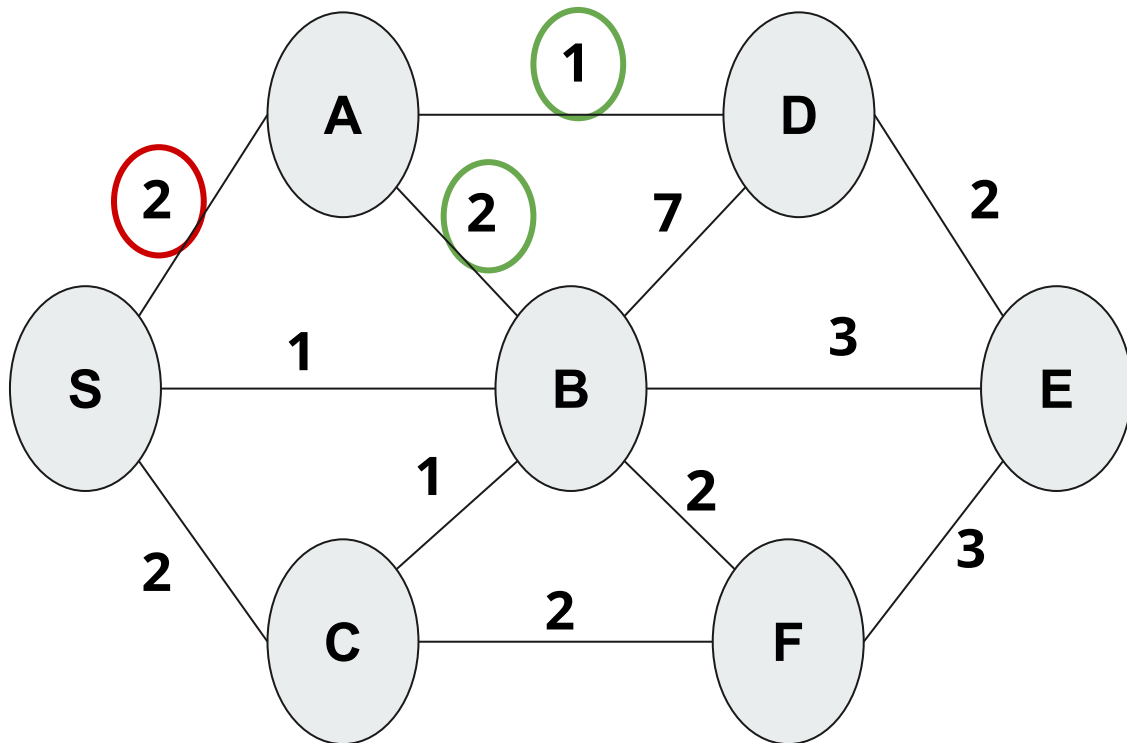
# Step 1: Construction of Cost Matrix



	S	A	B	C	D	E	F
S		2	1	2			
A							
B		3		2	8	4	3
C							
D							
E							
F							

COST MATRIX

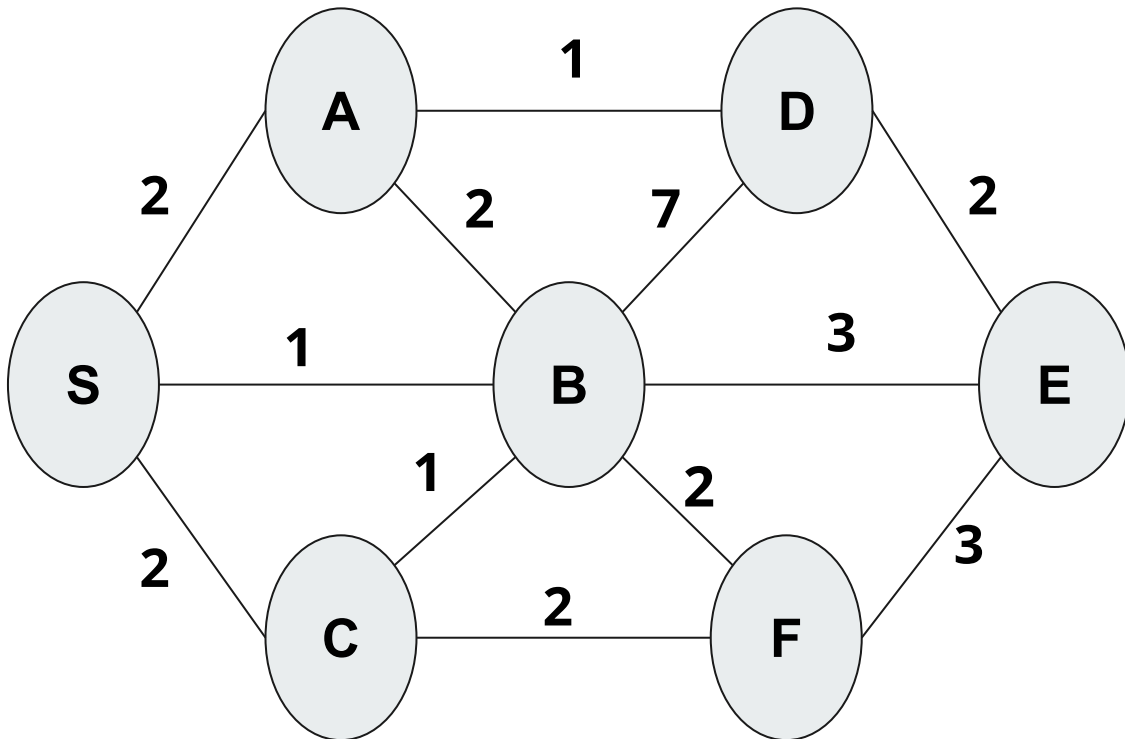
# Step 1: Construction of Cost Matrix



	S	A	B	C	D	E	F
S		2	1	2			
A			4		3		
B		3		2	8	4	3
C							
D							
E							
F							

COST MATRIX

# Step 1: Construction of Cost Matrix



	S	A	B	C	D	E	F
S		2	1	2			
A			4		3		
B		3		2	8	4	3
C			3				4
D		4	10			5	
E			7		6		7
F			5	5		6	

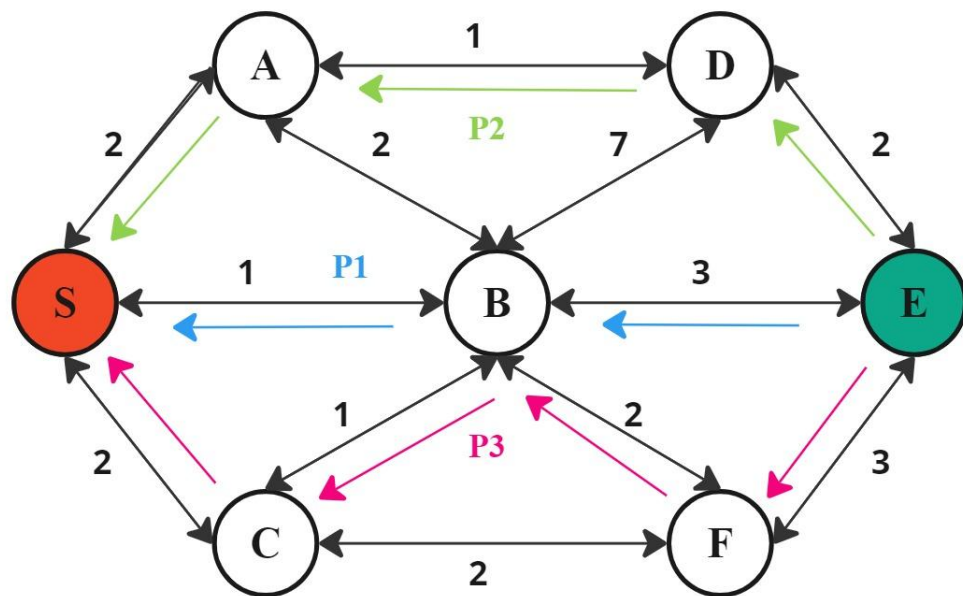
COST MATRIX



# Step 2: Construction of Disjoint Paths

From source: **S**  $\implies$  To destination: **E**

**E**  $\implies$  **B**  $\implies$  **S**



Construction of Disjoint Paths, Multiple Disjoint Path Algorithm

	S	A	B	C	D	E	F
S			1	2			
A			4		3		
B				2	8	inf	3
C			3				4
D			10			5	
E			inf		6		7
F			5	5		6	

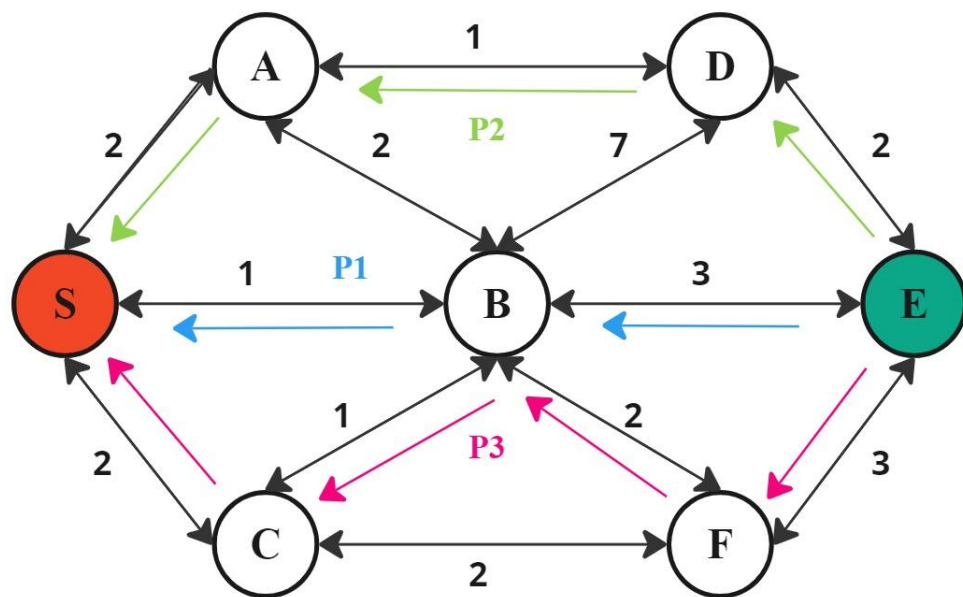
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# Step 2: Construction of Disjoint Paths

From source: **S**  $\implies$  To destination: **E**

**E**  $\implies$  **D**  $\implies$  **A**  $\implies$  **S**



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Construction of Disjoint Paths, Multiple Disjoint Path Algorithm

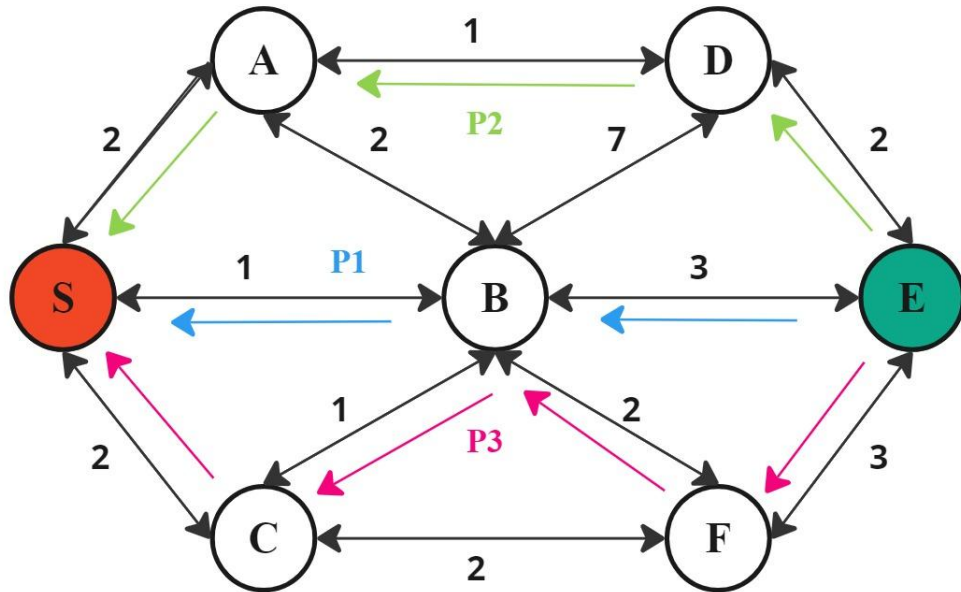
	S	A	B	C	D	E	F
S		2	inf	2			
A			4		inf		
B		3		2	8	inf	3
C			3				4
D		inf	10			inf	
E			inf		6		7
F			5	5		6	

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# Step 2: Construction of Disjoint Paths

From source: **S**  $\implies$  To destination: **E**

**E**  $\implies$  **F**  $\implies$  **B**  $\implies$  **C**  $\implies$  **S**



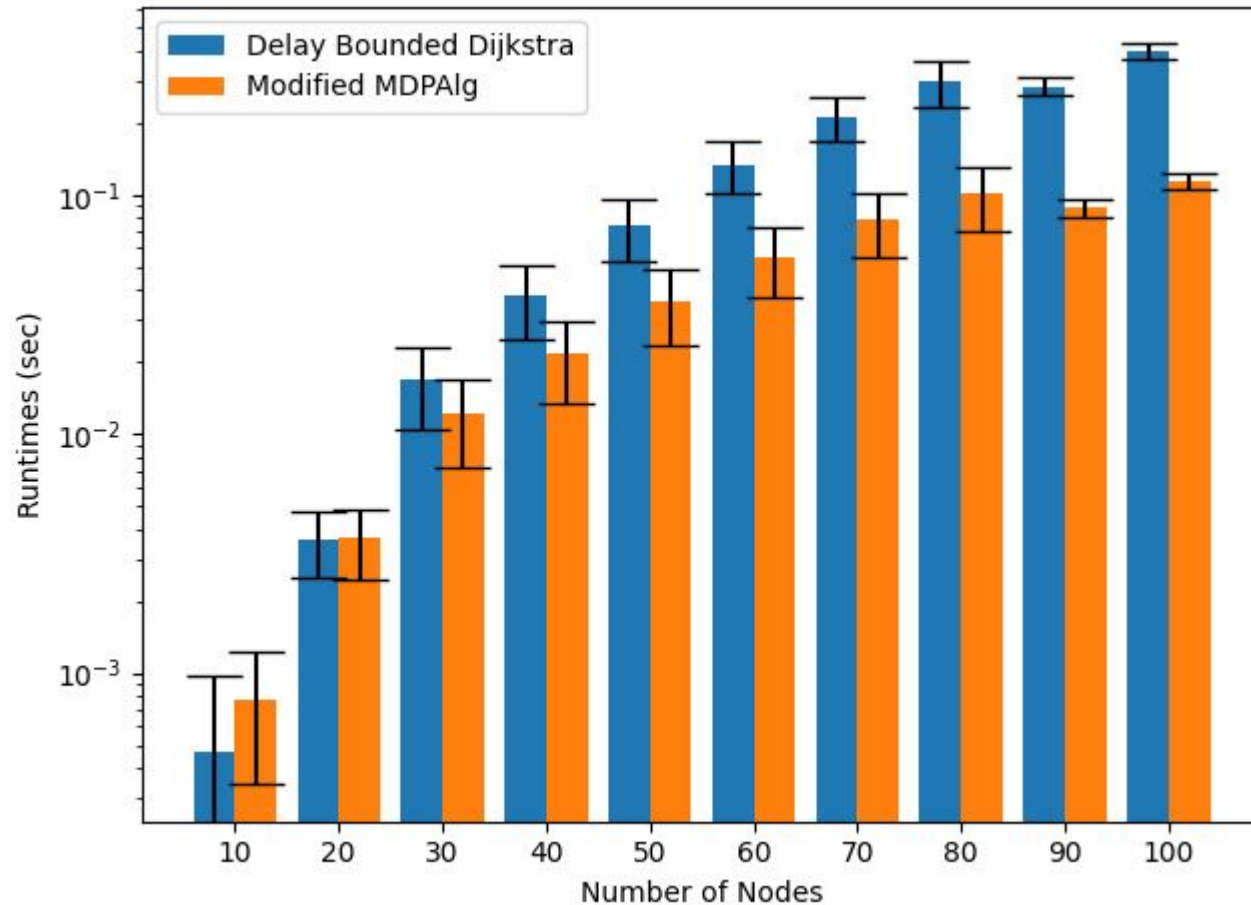
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Construction of Disjoint Paths, Multiple Disjoint Path Algorithm

	S	A	B	C	D	E	F
S		inf	inf	2			
A			4		inf		
B		3		2	8	inf	3
C			3				4
D		inf	10			inf	
E			inf		6		7
F			5	5		6	

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# Results



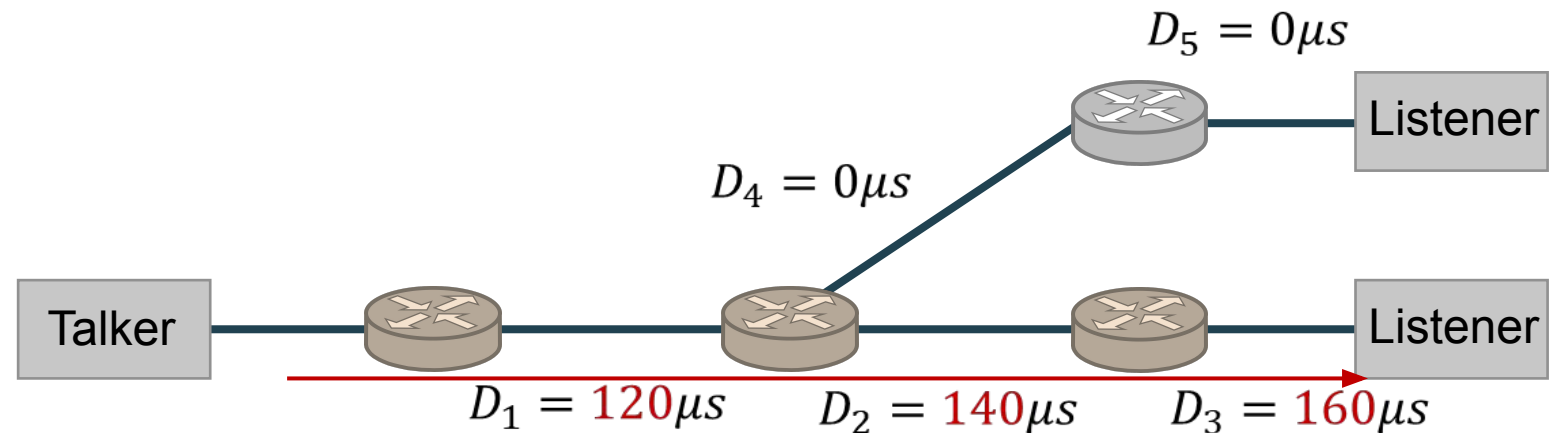
## Test Case Parameters:

- Randomly generated 1000 Fully-connected graphs with 10, 20, 30, ....., 100 Nodes.
- Randomly generated link attributes (cost and delay).
- Randomly generated source-destination pair.

# Delay Constraints for Real-Time Communications

## Problem:

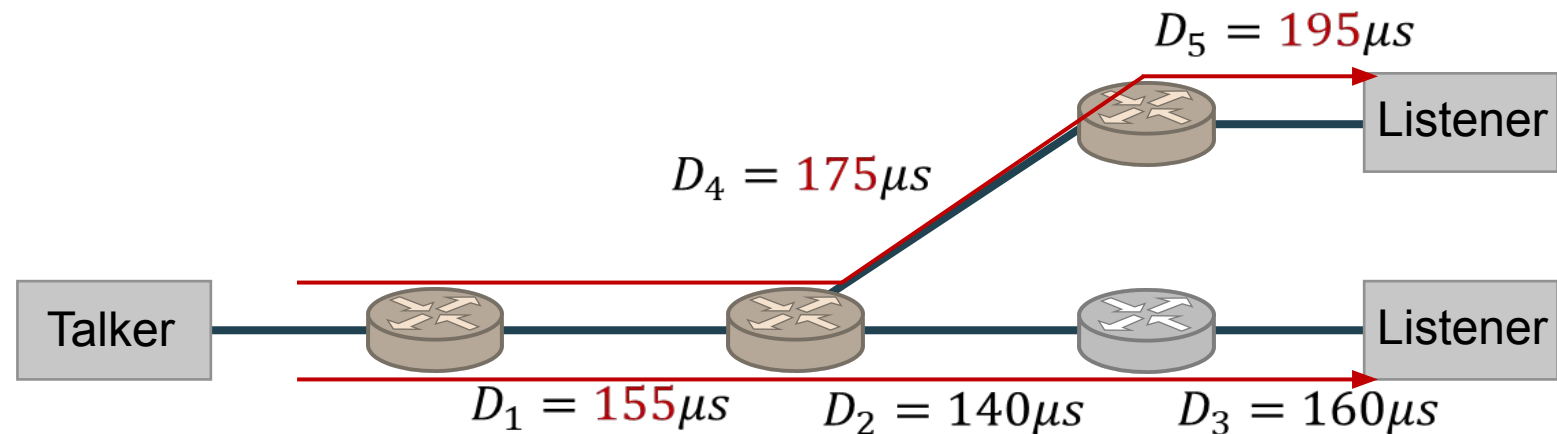
- Proposed routing algorithms run **iteratively** for each new flow in the network



# Delay Constraints for Real-Time Communications

## Problem:

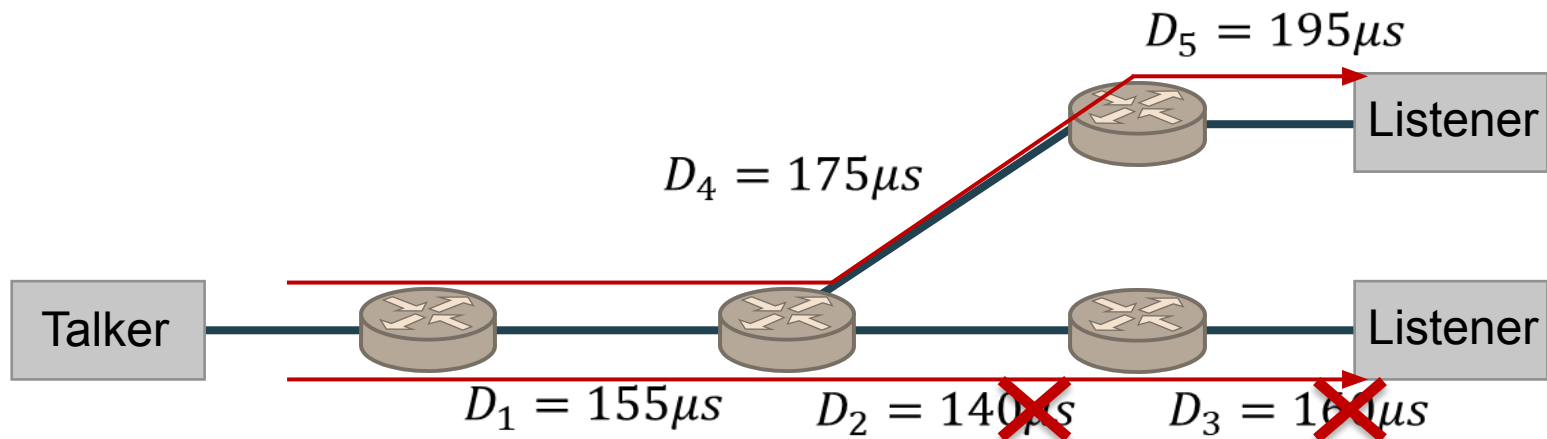
- Proposed routing algorithms run *iteratively* for each new flow in the network
- Delays at each hop depend on the flows in the network



# Delay Constraints for Real-Time Communications

## Problem:

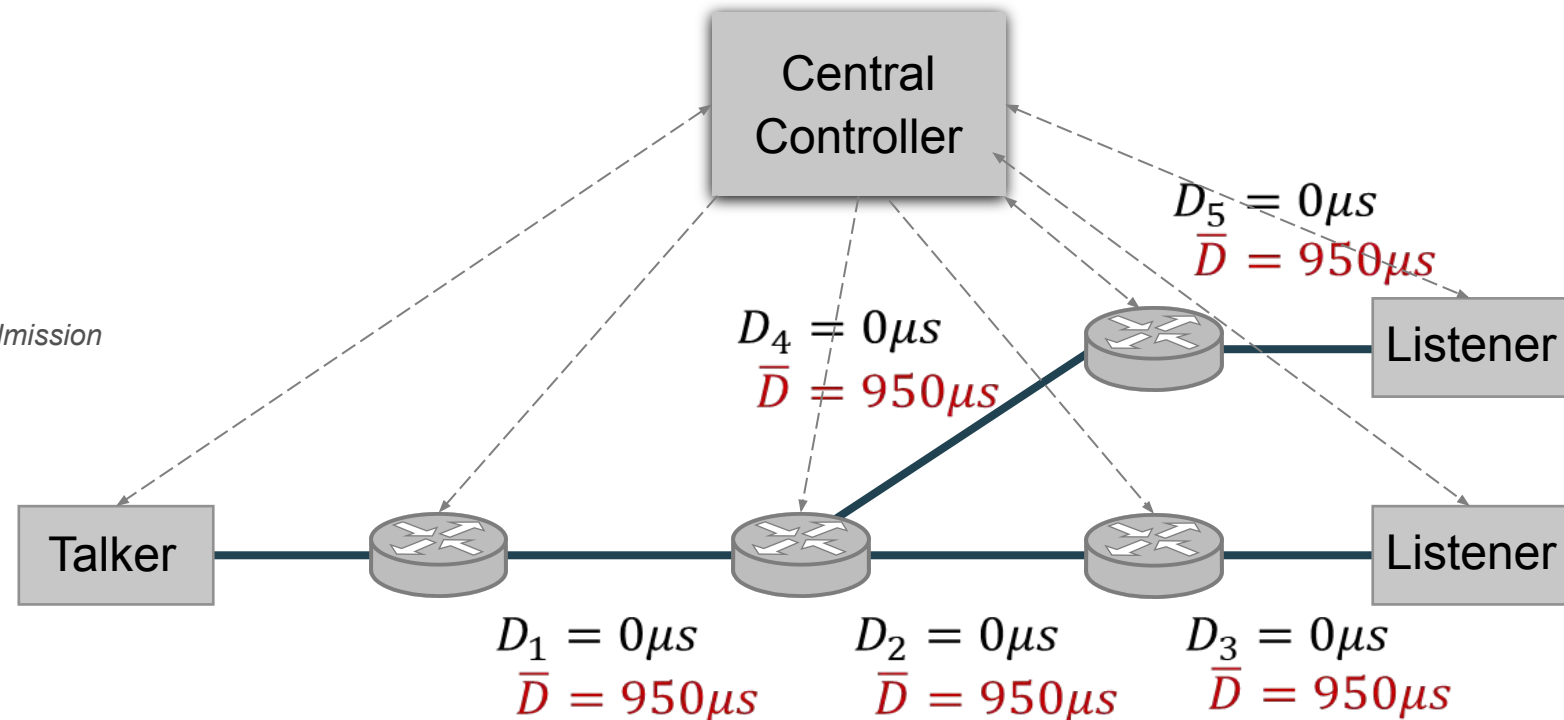
- Proposed routing algorithms run **iteratively** for each new flow in the network
  - Delays at each hop depend on the flows in the network
  - Delays for already reserved flows might no longer be valid after a new reservation
- **re-run routing algorithm for of all flows?**



# Delay Constraints for Real-Time Communications

## Solution:

- Central network controller to determine reservation-independent delay bounds  $\bar{D}$  [1]
- Used by the routing algorithms



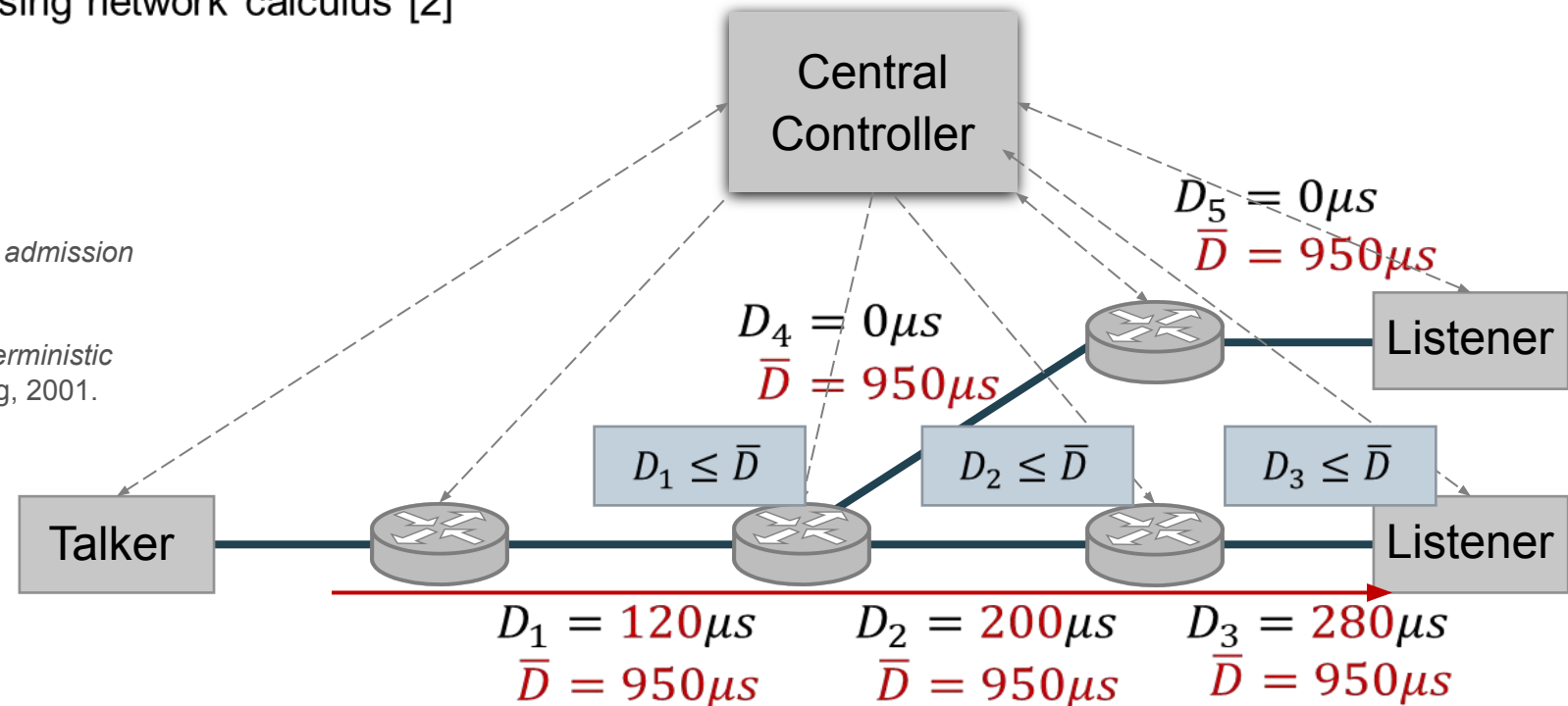
[1] L. Maile, K.-S. J. Hielscher, and R. German, "Delay-guaranteeing admission control for time-sensitive networking using the credit-based shaper," IEEE Open Journal of the Communications Society, vol. 3, 2022.



# Delay Constraints for Real-Time Communications

## Solution:

- Central network controller to determine reservation-independent delay bounds  $\bar{D}$  [1]
- Used by the routing algorithms
- Validated before each new reservation using network calculus [2]



[1] L. Maile, K.-S. J. Hielscher, and R. German, "Delay-guaranteeing admission control for time-sensitive networking using the credit-based shaper," IEEE Open Journal of the Communications Society, vol. 3, 2022.  
 [2] J.-Y. Le Boudec and P. Thiran, "Network calculus: A theory of deterministic queuing systems for the Internet". Berlin, Heidelberg: Springer-Verlag, 2001.

# Conclusion

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- Most of the disjoint routing algorithms are constrained to finding **only one pair** of shortest paths.
- **Computational complexity** of Dijkstra's Algorithm explodes in huge networks. Therefore not suitable for disjoint routing problems.
- Multiple Disjoint Path Algorithm proposes an innovative way of finding disjoint paths in a network through **single full graph search**.
- MDPAlg can be easily modified to make it useful for multicast transmission.

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# Thank You

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